

# First Two Weeks

#### Flora Zhou

**Research Experience for Undergrads** 

07/04/2024

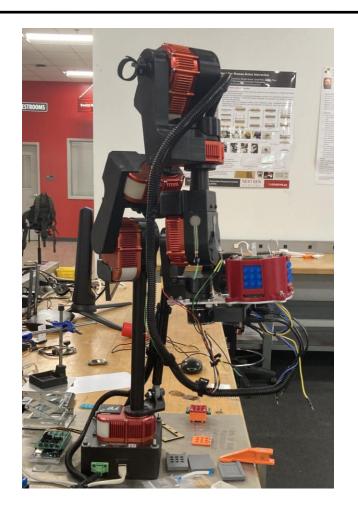


## **Background & Goals**



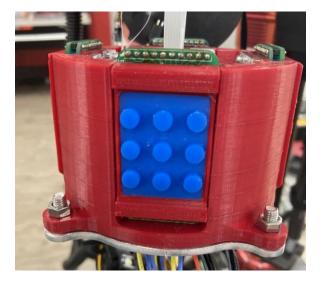
Mentor: Jordan Dowdy

- □ OctoCan:
- Intuitive, reliable, and safe physical human-robot interaction requires tactile information for the robot
- □ Summer Goals:
- □ 1. Patch (Sensor) Testing
- □ 2. Mount Design with CAD
- □ 3. Subject Testing



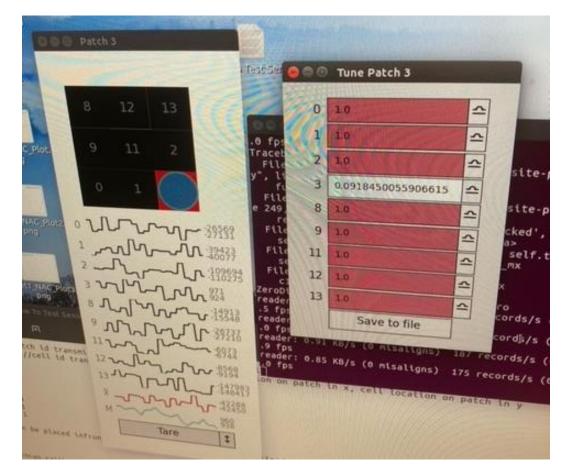
### **Sensor Testing**





Patch 5 at the front (Patch 3 is at the left side)

Patch 3 was being tested ->











This is where to install the mount

The original CAD design

Printed out

#### Future

Gantt Chart			
	Project Start Date	Project End Date	Today's Date
	6/20/24	8/11/24	7/3/24
		E de Bata	
Task Description	Start Date	End Date	% complete
Mount Design with CAD & Printing	6/26/24		
Sensor Testing	6/20/24	7/17/24	25
Subject Testing: Trace the robot arm	7/17/24	8/11/24	0
Mount Design with CAD & Printing - Sensor Testing - Subject Testing: - Trace the robot arm $-$ $b^{\Omega^2} b^{\Omega^0} b^{\Omega^0} 1^{\Omega} 1^{\delta} 1^{\delta}$		59 912 918 911 9120	completed remaining